

G	$= 6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$	$x - x_0$	$= vt - \frac{1}{2}at^2$
g	$= 9.8\text{m/s}^2$	a_x	$= a \cos \theta$
c	$= 3.00 \times 10^8 \text{m/s}$	a_y	$= a \sin \theta$
R_{Earth}	$= 6.37 \times 10^3 \text{km}$	a	$= \sqrt{a_x^2 + a_y^2}$
M_{Earth}	$= 5.97 \times 10^{24} \text{kg}$	$\tan \theta$	$= \frac{a_y}{a_x}$
ρ_{ice}	$= 0.92 \times 10^3 \text{kg/m}^3$	θ_A	$= \tan^{-1} \frac{A_y}{A_x} [\dots + 180^\circ]$
ρ_{water}	$= 1.00 \times 10^3 \text{kg/m}^3$	$\vec{a} \cdot \vec{b}$	$= ab \cos \phi$
ρ_{blood}	$= 1.06 \times 10^3 \text{kg/m}^3$	$\vec{a} \cdot \vec{b}$	$= A_x B_x + A_y B_y + A_z B_z$
ρ_{lead}	$= 11.3 \times 10^3 \text{kg/m}^3$	$\vec{a} \times \vec{b}$	$= \vec{c}$
N_A	$= 6.02 \times 10^{23} \text{mol}^{-1}$	c	$= ab \sin \phi$
m_e	$= 9.11 \times 10^{-31} \text{kg}$	\vec{v}	$= \frac{d\vec{r}}{dt}$
m_p	$= 1.67 \times 10^{-27} \text{kg}$	\vec{a}	$= \frac{d\vec{v}}{dt}$
1 m	$= 3.28 \text{ft}$	$x - x_0$	$= v_{0x}t$
1 inch	$= 2.54 \text{cm}$	$y - y_0$	$= v_{0y}t - \frac{1}{2}gt^2$
1 mi	$= 5280 \text{ft}$	y	$= (\tan \theta_0) x - \frac{gx^2}{2(v_0 \cos \theta_0)^2}$
1 lb	$= 4.45 \text{N}$	R	$= \frac{v_0^2}{g} \sin(2\theta_0)$
1 atm	$= 1.013 \times 10^5 \text{Pa}$	a	$= \frac{r}{4\pi^2 r}$
$\frac{d}{dx}(au)$	$= a \frac{du}{dx}$	a	$= \frac{T^2}{2\pi r}$
$\frac{d}{dx}(u+v)$	$= \frac{du}{dx} + \frac{dv}{dx}$	T	$= \frac{v}{v}$
$\frac{d}{dx}x^m$	$= mx^{m-1}$	$\Sigma \vec{F}$	$= m\vec{a}$
$\frac{d}{dx}(uv)$	$= u \frac{dv}{dx} + v \frac{du}{dx}$	W	$= mg$
$\int dx$	$= x$	\vec{F}_{AB}	$= -\vec{F}_{BA}$
$\int au dx$	$= a \int u dx$	f_s	$= \mu_s N$
$\int (u+v) dx$	$= \int u dx + \int v dx$	f_k	$= \mu_k N$
$\int x^m dx$	$= \frac{x^{m+1}}{m+1} \quad (m \neq -1)$	F	$= \frac{mv^2}{r}$
Δx	$= x_2 - x_1$	K	$= \frac{1}{2}mv^2$
\bar{v}	$= \frac{\Delta x}{\Delta t} = \frac{x_2 - x_1}{t_2 - t_1}$	ΔK	$= K_f - K_i = W$
\bar{s}	$= \frac{\text{total distance}}{\Delta t}$	W	$= Fd \cos \phi$
v	$= \frac{dx}{dt}$	W	$= \vec{F} \cdot \vec{d}$
\bar{a}	$= \frac{\Delta v}{\Delta t} = \frac{v_2 - v_1}{t_2 - t_1}$	W_g	$= mgd \cos \phi$
a	$= \frac{dv}{dt}$	ΔK	$= W_a + W_g$
v	$= v_0 + at$	W	$= \int_{x_i}^{x_f} F(x) dx$
$x - x_0$	$= v_0 t + \frac{1}{2}at^2$	F	$= -kx$
v^2	$= v_0^2 + 2a(x - x_0)$	W_s	$= -\frac{1}{2}kx^2$
$x - x_0$	$= \frac{1}{2}(v_0 + v)t$		

$$\begin{aligned}
\bar{P} &= \frac{W}{\Delta t} \\
P &= \frac{dW}{dt} \\
P &= \vec{F} \cdot \vec{v} \\
U &= mgy \\
U(x) &= \frac{1}{2}kx^2 \\
E &= K + U \\
F(x) &= -\frac{dU(x)}{dx} \\
W_{\text{app}} &= \Delta E \\
\Delta E &= -f_k d \\
P &= \frac{dE}{dt} \\
x_{\text{com}} &= \frac{1}{M} \sum_{i=1}^n m_i x_i \\
\vec{r}_{\text{com}} &= \frac{1}{M} \sum_{i=1}^n m_i \vec{r}_i \\
x_{\text{com}} &= \frac{1}{M} \int x \, dm \\
x_{\text{com}} &= \frac{1}{V} \int x \, dV \\
\Sigma \vec{F}_{\text{ext}} &= M \vec{a}_{\text{cm}} \\
\vec{p} &= m \vec{v} \\
\Sigma \vec{F} &= \frac{d\vec{p}}{dt} \\
\vec{P} &= M \vec{v}_{\text{cm}} \\
\Sigma \vec{F}_{\text{ext}} &= \frac{d\vec{P}}{dt} \\
\vec{P} &= \text{constant} \\
\vec{J} &= \int_{t_i}^{t_f} \vec{F}(t) \, dt \\
\vec{p}_f - \vec{p}_i &= \Delta \vec{p} = \vec{J} \\
v_{1f} &= \frac{m_1 - m_2}{m_1 + m_2} v_{1i} \\
v_{2f} &= \frac{2m_1}{m_1 + m_2} v_{1i} \\
v_{\text{cm}} &= \frac{P}{m_1 + m_2} \\
\theta &= \frac{s}{r} \\
\Delta \theta &= \theta_2 - \theta_1 \\
\omega &= \frac{d\theta}{dt} \\
\alpha &= \frac{d\omega}{dt} \\
\omega &= \omega_0 + \alpha t \\
\theta - \theta_0 &= \omega_0 t + \frac{1}{2} \alpha t^2 \\
\omega^2 &= \omega_0^2 + 2\alpha (\theta - \theta_0)
\end{aligned}$$

$$\begin{aligned}
\theta - \theta_0 &= \frac{1}{2} (\omega_0 + \omega) t \\
\theta - \theta_0 &= \omega t - \frac{1}{2} \alpha t^2 \\
s &= \theta r \\
v &= \omega r \\
a_t &= \alpha r \\
a_r &= \frac{v^2}{r} = \omega^2 r \\
I &= \Sigma m_i r_i^2 \\
I &= \int r^2 \, dm \\
K &= \frac{1}{2} I \omega^2 \\
\tau &= r F \sin \phi \\
\tau &= I \alpha \\
\Sigma \tau &= I \alpha \\
v_{\text{cm}} &= \omega R \\
K &= \frac{1}{2} I_{\text{cm}} \omega^2 + \frac{1}{2} M v_{\text{cm}}^2 \\
\vec{\tau} &= \vec{r} \times \vec{F} \\
\vec{l} &= \vec{r} \times \vec{p} = m (\vec{r} \times \vec{v}) \\
\Sigma \vec{\tau} &= \frac{d\vec{l}}{dt} \\
L &= I \omega \\
F &= G \frac{m_1 m_2}{r^2} \\
U &= -G \frac{m_1 m_2}{r} \\
v_{\text{esc}} &= \sqrt{\frac{2GM}{R}} \\
v_{\text{orb}} &= \sqrt{\frac{GM}{R}} \\
R_S &= \frac{c^2}{2GM} \\
T &= 1/f \\
\omega &= 2\pi f \\
k &= \frac{2\pi}{\lambda} \\
v &= \lambda f \\
\rho &= \frac{\Delta m}{\Delta V} \\
p &= \frac{\Delta F}{\Delta A} \\
p_2 &= p_1 + \rho g (y_1 - y_2) \\
p &= p_0 + \rho g h \\
F_B &= \rho_{\text{fl}} V_{\text{sub}} g \\
A_1 v_1 &= A_2 v_2 \\
p_1 + \frac{1}{2} \rho v_1^2 + \rho g y_1 &= p_2 + \frac{1}{2} \rho v_2^2 + \rho g y_2
\end{aligned}$$