

$G$	$=$	$6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$	$a_x$	$=$	$a \cos \theta$
$g$	$=$	$9.8 \text{ m/s}^2$	$a_y$	$=$	$a \sin \theta$
$c$	$=$	$3.00 \times 10^8 \text{ m/s}$	$a$	$=$	$\sqrt{a_x^2 + a_y^2}$
$R_{\text{Earth}}$	$=$	$6.37 \times 10^3 \text{ km}$	$\tan \theta$	$=$	$\frac{a_y}{a_x}$
$M_{\text{Earth}}$	$=$	$5.97 \times 10^{24} \text{ kg}$	$\theta_A$	$=$	$\tan^{-1} \frac{A_y}{A_x} [\dots + 180^\circ]$
$\rho_{\text{air}}$	$=$	$1.225 \text{ kg/m}^3$	$\vec{a} \cdot \vec{b}$	$=$	$ab \cos \phi$
$\rho_{\text{ice}}$	$=$	$0.92 \times 10^3 \text{ kg/m}^3$	$\vec{a} \cdot \vec{b}$	$=$	$A_x B_x + A_y B_y + A_z B_z$
$\rho_{\text{water}}$	$=$	$1.00 \times 10^3 \text{ kg/m}^3$	$\vec{a} \times \vec{b}$	$=$	$\vec{c}$
$\rho_{\text{blood}}$	$=$	$1.06 \times 10^3 \text{ kg/m}^3$	$c$	$=$	$ab \sin \phi$
$\rho_{\text{lead}}$	$=$	$11.3 \times 10^3 \text{ kg/m}^3$	$\vec{v}$	$=$	$\frac{d\vec{r}}{dt}$
$N_A$	$=$	$6.02 \times 10^{23} \text{ mol}^{-1}$	$\vec{a}$	$=$	$\frac{d\vec{v}}{dt}$
$m_e$	$=$	$9.11 \times 10^{-31} \text{ kg}$	$x - x_0$	$=$	$v_{0x} t$
$m_p$	$=$	$1.67 \times 10^{-27} \text{ kg}$	$y - y_0$	$=$	$v_{0y} t - \frac{1}{2} g t^2$
1 m	$=$	3.28 ft	$y$	$=$	$(\tan \theta_0) x - \frac{g x^2}{2 (v_0 \cos \theta_0)^2}$
1 inch	$=$	2.54 cm	$R$	$=$	$\frac{v_0^2}{g} \sin(2\theta_0)$
1 mi	$=$	5280 ft	$a$	$=$	$\frac{r}{v^2}$
1 lb	$=$	4.45 N	$a$	$=$	$\frac{4\pi^2 r}{T^2}$
1 atm	$=$	$1.013 \times 10^5 \text{ Pa}$	$T$	$=$	$\frac{2\pi r}{v}$
$C = 2\pi r$	$A = \pi r^2$	$SA = 4\pi r^2$	$\Sigma \vec{F}$	$=$	$m\vec{a}$
		$V = \frac{4}{3}\pi r^3$	$W$	$=$	$mg$
$\frac{d}{dx}(au)$	$=$	$a \frac{du}{dx}$	$\vec{F}_{AB}$	$=$	$-\vec{F}_{BA}$
$\frac{d}{dx}(u+v)$	$=$	$\frac{du}{dx} + \frac{dv}{dx}$	$f$	$=$	$\mu N$
$\frac{d}{dx}(uv)$	$=$	$u \frac{dv}{dx} + v \frac{du}{dx}$	$F$	$=$	$\frac{mv^2}{r}$
$\int dx$	$=$	$x$	$K$	$=$	$\frac{1}{2}mv^2$
$\int au \, dx$	$=$	$a \int u \, dx$	$\Delta K$	$=$	$K_f - K_i = W$
$\int x^m \, dx$	$=$	$\frac{x^{m+1}}{m+1} \quad (m \neq -1)$	$W$	$=$	$F d \cos \phi$
$\Delta x$	$=$	$\frac{x_2 - x_1}{\Delta t} = \frac{x_2 - x_1}{t_2 - t_1}$	$W$	$=$	$\vec{F} \cdot \vec{d}$
$\bar{v}$	$=$	$\frac{\text{total distance}}{\Delta t}$	$W_g$	$=$	$mgd \cos \phi$
$\bar{s}$	$=$	$\frac{dx}{dt}$	$\Delta K$	$=$	$W_a + W_g$
$v$	$=$	$\frac{\Delta v}{\Delta t} = \frac{v_2 - v_1}{t_2 - t_1}$	$W$	$=$	$\int_{x_i}^{x_f} F(x) \, dx$
$\bar{a}$	$=$	$\frac{dv}{dt}$	$F$	$=$	$-kx$
$a$	$=$	$\frac{dv}{dt}$	$W_s$	$=$	$-\frac{1}{2}kx^2$
$v$	$=$	$v_0 + at$	$\bar{P}$	$=$	$\frac{W}{\Delta t}$
$x - x_0$	$=$	$v_0 t + \frac{1}{2}at^2$	$P$	$=$	$\frac{dW}{dt}$
$v^2$	$=$	$v_0^2 + 2a(x - x_0)$			
$x - x_0$	$=$	$\frac{1}{2}(v_0 + v)t$			
$x - x_0$	$=$	$vt - \frac{1}{2}at^2$			

$$\begin{aligned}
P &= \vec{F} \cdot \vec{v} & a_r &= \frac{v^2}{r} = \omega^2 r \\
U &= mgy & I &= \sum m_i r_i^2 \\
U(x) &= \frac{1}{2} kx^2 & I &= \int r^2 dm \\
E &= K + U & K &= \frac{1}{2} I \omega^2 \\
F(x) &= -\frac{dU(x)}{dx} & \tau &= rF \sin \phi \\
W_{\text{app}} &= \Delta E & \tau &= I\alpha \\
\Delta E &= -f_k d & \Sigma \tau &= I\alpha \\
P &= \frac{dE}{dt} & v_{cm} &= \omega R \\
x_{\text{com}} &= \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2} & K &= \frac{1}{2} I_{cm} \omega^2 + \frac{1}{2} M v_{cm}^2 \\
x_{\text{com}} &= \frac{1}{M} \int x dm & \vec{\tau} &= \vec{r} \times \vec{F} \\
x_{\text{com}} &= \frac{1}{V} \int x dV & \vec{l} &= \vec{r} \times \vec{p} = m (\vec{r} \times \vec{v}) \\
\Sigma \vec{F}_{\text{ext}} &= M \vec{a}_{\text{cm}} & \Sigma \vec{\tau} &= \frac{d\vec{l}}{dt} \\
\vec{p} &= m \vec{v} & L &= I \omega \\
\Sigma \vec{F} &= \frac{d\vec{p}}{dt} & \rho &= \frac{\Delta V}{\Delta F} \\
\vec{P} &= M \vec{v}_{\text{cm}} & p &= \frac{\Delta A}{\Delta A} \\
\Sigma \vec{F}_{\text{ext}} &= \frac{d\vec{P}}{dt} & p_2 &= p_1 + \rho g (y_1 - y_2) \\
\vec{P} &= \text{constant} & p &= p_0 + \rho g h \\
\vec{J} &= \int_{t_i}^{t_f} \vec{F}(t) dt & F_B &= \rho_{\text{fl}} V_{\text{sub}} g \\
\vec{p}_f - \vec{p}_i &= \Delta \vec{p} = \vec{J} & A_1 v_1 &= A_2 v_2 \\
v_{1f} &= \frac{m_1 - m_2}{m_1 + m_2} v_{1i} & p_1 + \frac{1}{2} \rho v_1^2 + \rho g y_1 &= p_2 + \frac{1}{2} \rho v_2^2 + \rho g y_2 \\
v_{2f} &= \frac{2m_1}{m_1 + m_2} v_{1i} & F &= G \frac{m_1 m_2}{r^2} \\
v_{cm} &= \frac{P}{m_1 + m_2} & U &= -G \frac{m_1 m_2}{r} \\
\theta &= \frac{s}{r} & v_{\text{esc}} &= \sqrt{\frac{2GM}{R}} \\
\Delta \theta &= \theta_2 - \theta_1 & v_{\text{orb}} &= \sqrt{\frac{GM}{r}} \\
\omega &= \frac{d\theta}{dt} & R_S &= \frac{r}{c^2} \\
\alpha &= \frac{d\omega}{dt} & T &= 1/f \\
\omega &= \omega_0 + \alpha t & \omega &= 2\pi f \\
\theta - \theta_0 &= \omega_0 t + \frac{1}{2} \alpha t^2 & k &= \frac{2\pi}{\lambda} \\
\omega^2 &= \omega_0^2 + 2\alpha (\theta - \theta_0) & v &= \lambda f \\
\theta - \theta_0 &= \frac{1}{2} (\omega_0 + \omega) t & y(x, t) &= A \cos \left( \frac{2\pi}{\lambda} x - \omega t \right) \\
\theta - \theta_0 &= \omega t - \frac{1}{2} \alpha t^2 & f_n &= n \frac{v}{2L} \quad \text{fixed string or open pipe} \\
s &= \theta r & f_n &= n \frac{v}{4L} \quad \text{stopped pipe} \\
v &= \omega r & f_{\text{beat}} &= \frac{f_a - f_b}{v + v_L} \\
a_t &= \alpha r & f_L &= \frac{v + v_S}{v + v_S} f_S
\end{aligned}$$