$$G = 6.67\times10^{-11}\ N\cdot m^2/kg^2$$
$$g = 9.8 m/s^2$$
$$c = 3.00\times10^{8} m/s$$
$$m_{\rm e} = 9.11\times10^{-31}\ kg$$
$$m_{\rm p} = 1.67\times10^{-27}\ kg$$
$$1\text{ m} = 3.28\text{ ft}$$
$$1\text{ lb} = 4.45\ N$$
$$\frac{d}{dx}x = 1$$
$$\frac{d}{dx}(au) = a\frac{du}{dx}$$
$$\frac{d}{dx}(u+v) = \frac{du}{dx}+\frac{dv}{dx}$$
$$\frac{d}{dx}x^m = mx^{m-1}$$
$$\frac{d}{dx}(uv) = u\frac{dv}{dx}+v\frac{du}{dx}$$
$$\int dx = x$$
$$\int au\ dx = a\int u\ dx$$
$$\int (u+v)\,dx = \int u\ dx+\int v\ dx$$
$$\int x^m\ dx = \frac{x^{m+1}}{m+1}\quad (m\neq -1)$$
$$\Delta x = x_2 - x_1$$
$$\bar{v} = \frac{\Delta x}{\Delta t}=\frac{x_2-x_1}{t_2-t_1}$$
$$\bar{s} = \frac{\text{total distance}}{\Delta t}$$
$$v = \frac{dx}{dt}$$
$$\bar{a} = \frac{\Delta v}{\Delta t}=\frac{v_2-v_1}{t_2-t_1}$$
$$a = \frac{dv}{dt}$$
$$v = v_0 + at$$
$$x - x_0 = v_0 t+\frac{1}{2}at^2$$
$$v^2 = v_0^2+2a(x-x_0)$$
$$x - x_0 = \frac{1}{2}(v_0+v)\,t$$
$$x - x_0 = vt-\frac{1}{2}at^2$$
$$a_x = a\cos\theta$$
$$a_y = a\sin\theta$$
$$a = \sqrt{a_x^2+a_y^2}$$
$$\tan\theta = \frac{a_y}{a_x}$$
$$\vec{a}\cdot\vec{b} = ab\cos\phi$$
$$c = ab\sin\phi$$
$$\vec{v} = \frac{d\vec{r}}{dt}$$
$$\vec{a} = \frac{d\vec{v}}{dt}$$
$$x - x_0 = v_{0x}t$$
$$y - y_0 = v_{0y}t-\frac{1}{2}gt^2$$
$$y = (\tan\theta_0)\,x-\frac{gx^2}{2\,(v_0\cos\theta_0)^2}$$
$$R = \frac{v_0^2}{g}\sin(2\theta_0)$$
$$a = \frac{v^2}{r}$$
$$T = \frac{2\pi r}{v}$$
$$\Sigma\vec{F} = m\vec{a}$$
$$W = mg$$
$$\vec{F}_{\rm AB} = -\vec{F}_{\rm BA}$$
$$f_s = \mu_s N$$
$$f_k = \mu_k N$$
$$F = \frac{mv^2}{r}$$
$$K = \frac{1}{2}mv^2$$
$$\Delta K = K_f - K_i = W$$
$$W = Fd\cos\phi$$
$$W = \vec{F}\cdot\vec{d}$$
$$W_g = mgd\cos\phi$$
$$\Delta K = W_a + W_g$$
$$W = \int_{x_i}^{x_f}F(x)\ dx$$
$$F = -kx$$
$$W_s = -\frac{1}{2}kx^2$$
$$\bar{P} = \frac{W}{\Delta t}$$
$$P = \frac{dW}{dt}$$
$$P = \vec{F}\cdot\vec{v}$$
$$U = mgy$$
$$U(x) = \frac{1}{2}kx^2$$
$$E = K+U$$
$$F(x) = -\frac{dU(x)}{dx}$$
$$W_{\rm app} = \Delta E$$
$$\Delta E = -f_k d$$
$$P = \frac{dE}{dt}$$
$$x_{\rm com} = \frac{1}{M}\Sigma_{i=1}^n m_i x_i$$
$$\vec{r}_{\rm com} = \frac{1}{M}\Sigma_{i=1}^n m_i \vec{r}_i$$
$$\Sigma\vec{F}_{\rm ext} = M\vec{a}_{\rm cm}$$
$$\vec{p} = m\vec{v}$$
$$\Sigma\vec{F} = \frac{d\vec{p}}{dt}$$
$$\vec{P} = M\vec{v}_{\rm cm}$$
$$\Sigma\vec{F}_{\rm ext} = \frac{d\vec{P}}{dt}$$
$$\vec{P} = \text{constant}$$
$$\theta = \tfrac{s}{r}$$
$$\Delta\theta = \theta_2-\theta_1$$
$$\omega = \frac{d\theta}{dt}$$
$$\alpha = \frac{d\omega}{dt}$$
$$\omega = \omega_0+\alpha t$$
$$\theta-\theta_0 = \omega_0 t+\frac{1}{2}\alpha t^2$$

$$
\begin{aligned}
\omega^2 &= \omega_0^2 + 2\alpha\left(\theta - \theta_0\right) \\
\theta - \theta_0 &= \frac{1}{2}\left(\omega_0 + \omega\right)t \\
\theta - \theta_0 &= \omega t - \frac{1}{2}\alpha t^2 \\
s &= \theta r \\
v &= \omega r \\
a_t &= \alpha r \\
a_r &= \frac{v^2}{r} = \omega^2 r \\
I &= \Sigma m_i r_i^2 \\
K &= \frac{1}{2} I \omega^2 \\
\tau &= rF\sin\phi \\
\tau &= I\alpha \\
\Sigma\tau &= I\alpha \\
F &= G\frac{m_1 m_2}{r^2} \\
U &= -G\frac{m_1 m_2}{r} \\
v &= \sqrt{\frac{2GM}{R}} \\
\rho &= \frac{\Delta m}{\Delta V} \\
p &= \frac{\Delta F}{\Delta A} \\
p_2 &= p_1 + \rho g\left(y_1 - y_2\right) \\
p &= p_0 + \rho g h
\end{aligned}
$$